

CARRY OUT MECHATRONIC PROGRAMMING

UNIT CODE: ENG/OS/MC/CR/05/6/A

Unit description

This unit describes the competencies required by a technician in order to carry out mechatronic programming. It involves identifying mechatronic programming languages used in machines, developing and customizing a mechatronic program, testing and configuring a mechatronic program, interfacing a mechatronic program with system and maintain mechatronic program.

ELEMENTS AND PERFORMANCE CRITERIA

ELEMENT These describe the key outcomes which make up workplace function.	PERFORMANCE CRITERIA These are assessable statements which specify the required level of performance for each of the elements. <i>Bold and italicized terms are elaborated in the Range.</i>
1. Identify mechatronic programming languages used in machine	1.1 System manual is analysed according to manufacturer specifications 1.2 System software and hardware interface is established according to system specifications 1.3 System programmable hardware in use are identified according to system specifications 1.4 System software requirements are identified according to programmable hardware in use
2. Develop and customize a mechatronic program	2.1 Correct software is obtained according to the system requirements 2.2 Flow chart of activities is developed according to the task requirements 2.3 <i>Peripheral devices</i> to be used are identified according to software operational requirements 2.4 Inputs and outputs of peripheral devices are verified according system manual and program flow charts 2.5 <i>Mechatronic program</i> is generated and customized according to system requirements 2.6 Mechatronic program is run offline according to system specifications
3. Interface mechatronic program with system	3.1 Correct wiring of peripheral devices is verified according to system manual 3.2 Software and hardware is installed according to system requirements 3.3 Peripheral devices are installed according system specifications 3.4 Mechatronic program is networked with the system according to system requirements

	3.5 Mechatronic program and interface is documented according to SOPs
4. Test and configure mechatronic program	4.1 Mechatronic program is configured according to peripheral device inputs and outputs requirements 4.2 Mechatronic program is run online and tested for errors according to system requirements 4.3 Mechatronic program is debugged in the event of errors according system output
5. Maintain mechatronic program	5.1 Faults are diagnosed in the mechatronic program according to system manual 5.2 Faults in peripheral devices are diagnosed according to system manual 5.3 Mechatronic program is maintained according to system specifications 5.4 Peripheral devices are maintained according system specifications 5.5 Maintenance is scheduled according to manufacturer specifications

RANGE

This section provides work environments and conditions to which the performance criteria apply. It allows for different work environments and situations that will affect performance.

Variable	Range
Peripheral devices may include but is not limited to:	<ul style="list-style-type: none"> • Sensors • Actuators • Instruments • Integrated circuits • Controllers
Mechatronic program may include but is not limited to:	<ul style="list-style-type: none"> • PLC • SCADA • MATLAB

REQUIRED KNOWLEDGE

The individual needs to demonstrate knowledge of:

- Mechatronic software
- Networking

- Documentation
- Scheduling/planning for maintenance
- Logic
- Algorithms and data structures
- Programming languages
- Scientific methods

REQUIRED SKILLS

The individual needs to demonstrate skills in:

- Coding
- Communication skills
- Programming languages
- Problem solving
- Data collection and analysis
- Service and repair of system components
- Fault diagnosis
- Attention to details

EVIDENCE GUIDE

This provides advice on assessment and must be in conjunction with the performance criteria, required skills and knowledge and range.

1. Critical Aspects of Competency.	1.1 Identified mechatronic programming languages used in the machines 1.2 Developed and customized mechatronic programs 1.3 Tested and configured mechatronic programs 1.4 Interfaced mechatronic programs with systems in use 1.5 Maintained mechatronic programs
2. Resource Implications.	2.1 Computers 2.2 Software 2.3 Whiteboards 2.4 Whiteboard markers 2.5 Manuals 2.6 Controllers (PLCs etc.)
3. Methods of Assessment.	<i>Competency may be assessed through:</i> 3.1 Practical 3.2 Observation 3.3 Questionnaire 3.4 Case studies 3.5 Written examinations 3.6 Oral presentation

4. Context of Assessment.	4.1 Competency may be assessed individually in an actual workplace or in work-simulated conditions within accredited institutions.
5. Guidance information for assessment.	5.1 This unit may be assessed on an integrated basis with others within this occupational sector.

easytvvet.com